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Rock / Mine Classification Using Supervised Machine Learning Algorithms | IEEE Conference Publication | IEEE Xplore Date Added to IEEE Xplore: 10 April 2023

ISBN Information:

Publisher: IEEE

Conference Location: Bengaluru, India

Contents

I. Introduction

Sound Navigation and Ranging, or SONAR, is a type of unmanned vehicle which utilizes sound technology to detect submerged objects, navigate underwater, and communicate. The acoustics can range from infrasonic (low) to ultrasonic (high). Underwater acoustics, often known as hydro acoustics, is the study of underwater sound. Active sonar and passive sonar are the two types of SONAR. The non-passive transducers create some sound pulse into the water, which is used to detect underwater objects. In case some of the things available in the way of sound pulse, the echo resiles off of it and come back to the sonan the tice astia ue one adding signal strength is measured by the transducer if it is ready to receive signals. Several algorithms as decision tree, k nearest neighbor, support vectors and gradient boosting by [1] which isolates the underwater sea objects specifically mines or rocks to obtain zoomed imagery. Gradient Boosting classifier produced better accuracy and how SONAR technology works in underwater sea is illustrated in figure 1. Fig. 1.

SONAR technology in underwater seafloor.

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