

## **Chapter 9**

### **Study and Analysis of Automatic Track-Guided Vehicles for Industrial Applications**

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#### **Abstract:**

This paper outlines the design and construction of a module suitable for driving the vehicles in hill station. Auto braking system is used for vehicles going in upward direction. This construction includes of two phases. In first module, slope of the vehicle is observed using micro-electromechanical system (MEMS) Sensor and in second phase, motor speed is controlled based on the data from sensor. Sensor is interfaced to the microcontroller using 12c Protocol where the controller receives the information from the sensor and processes it according to the desired decisions. An automatic Braking system is an intelligent mechatronic system includes an Ultrasonic wave emitter provided on the front portion of a car producing and emitting Ultrasonic waves. An Ultrasonic receiver is also placed on the front portion of the car operatively receiving a reflective Ultrasonic wave signal. The reflected wave (detected pulse) gives the distance between the obstacle and the vehicle. Then a microcontroller is used to control the speed of the vehicle based on the detection pulse information to push the brake pedal and apply brake to the car stupendously for safety purpose.

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## **1. Introduction**

Hill stations, with their steep gradients, winding roads, and unpredictable weather conditions, present unique challenges for vehicle safety and control. In these rugged terrains, conventional braking systems often struggle to provide the precise control needed to navigate safely. To address these challenges, there is a growing need for advanced safety systems that can adapt to the dynamic driving conditions of hill stations. One promising solution is the development of an advanced safety brake system that integrates Micro-Electro-Mechanical System (MEMS) sensors with MPLAB X IDE for robust, real-time performance.

**Micro-Electro-Mechanical Systems (MEMS) Sensors:** MEMS sensors are pivotal in modern automotive safety systems due to their ability to measure physical parameters with high precision. These sensors can detect critical variables such as vehicle acceleration, tilt, and lateral forces, which are essential for understanding the vehicle's behavior on uneven and steep terrain. By incorporating MEMS sensors into the brake system, the vehicle can gain real-time insights into its dynamic state, allowing for more responsive and adaptive braking actions. This capability is crucial for maintaining stability and preventing accidents in challenging driving conditions.

**MPLAB X IDE:** The MPLAB X Integrated Development Environment (IDE) by Microchip Technology provides a powerful platform for developing and refining the firmware that controls MEMS sensors and the braking system. This development environment offers a suite of tools for coding, debugging, and optimizing embedded systems. With MPLAB X IDE, engineers can efficiently program the microcontrollers that process sensor data and execute braking commands. The IDE's comprehensive features support iterative testing and refinement, ensuring that the brake system operates reliably and effectively in real-world conditions.

**System Integration and Benefits:** Integrating MEMS sensors with MPLAB X IDE in the design of an advanced safety brake system allows for a sophisticated approach to managing vehicle stability and safety. The sensor data can be used to continuously monitor and adjust braking force, improving control and reducing the risk of skidding or loss of traction. Additionally, the ability to program and test the system using MPLAB X IDE ensures that the braking system can be fine-tuned to respond optimally to the specific demands of hill station driving.

This project aims to address the safety and performance needs of hill station vehicles by developing a brake system that leverages the precision of MEMS sensors and the flexibility of MPLAB X IDE. The result is a braking solution that not only enhances vehicle stability and driver confidence but also contributes to safer travel in some of the most challenging driving environments. By advancing automotive safety technology, this project represents a significant step towards more reliable and secure driving experiences in hill stations and similar terrains.

## **2. Micro-Electro-Mechanical Systems (MEMS) Sensors**

Micro-Electro-Mechanical Systems (MEMS) sensors are integral to modern automotive safety systems, providing precise and reliable data critical for optimizing vehicle control, especially in challenging driving environments such as hill stations. These sensors combine mechanical and electrical components on a single chip, enabling them to measure various physical parameters with high accuracy and sensitivity.

### **1. Functionality and Capabilities:**

- **Acceleration Measurement:** MEMS accelerometers measure the vehicle's acceleration along different axes. In the context of a hill station, they help detect sudden changes in speed or direction,

allowing the braking system to respond appropriately to steep gradients and sharp turns.

- **Tilt and Inclination Sensing:** MEMS gyroscopes and inclinometers detect the vehicle's tilt and orientation. This information is crucial for maintaining stability on sloped terrain, ensuring that the braking system can adapt to the vehicle's angle and prevent rollovers or skidding.
- **Lateral Force Detection:** MEMS sensors also measure lateral forces acting on the vehicle, which helps in assessing cornering forces and maintaining traction during turns. This capability is particularly important for navigating winding hill roads safely.

## **2. Integration in Brake Systems:**

- **Real-Time Data Processing:** MEMS sensors provide continuous, real-time data about the vehicle's dynamic conditions. This data is processed by the brake system's control unit to adjust braking force dynamically, enhancing vehicle stability and control. For instance, if the sensors detect excessive tilt or lateral forces, the system can apply additional braking to counteract these forces and maintain control.
- **Enhanced Safety Features:** By integrating MEMS sensors into the brake system, features such as automatic emergency braking and adaptive braking control can be significantly improved. The sensors' data enables the system to make quick, informed decisions about braking actions, reducing the risk of accidents in challenging conditions.

### 3. **Advantages and Challenges:**

- **Advantages:** MEMS sensors offer high precision, compact size, and low power consumption, making them well-suited for automotive applications. Their ability to measure multiple parameters simultaneously enhances the braking system's responsiveness and effectiveness. Additionally, their integration into a single chip reduces system complexity and cost.
- **Challenges:** Despite their advantages, MEMS sensors can face challenges such as sensitivity to environmental factors (e.g., temperature changes) and potential calibration issues. Ensuring accurate and reliable performance requires careful calibration and robust system design.

### 4. **Role in Advanced Safety Systems:**

- **Adaptive Brake Control:** MEMS sensors play a critical role in adaptive brake control systems by providing the data needed to adjust braking force based on real-time conditions. This ensures that the vehicle's brakes respond appropriately to varying terrain and driving conditions.
- **Improved Driver Assistance:** The data from MEMS sensors enhances various driver assistance systems, such as stability control and traction control, by providing detailed information about the vehicle's dynamic state. This improves overall driving safety and comfort, particularly in challenging hill station environments.

In summary, MEMS sensors are essential for developing an advanced safety brake system for hill station vehicles. Their precise measurement capabilities and real-time data processing enable the creation of a

braking system that adapts to the unique demands of steep and winding terrains, enhancing vehicle stability and driver safety.

### **3. MPLAB X IDE**

MPLAB X IDE is a powerful development environment designed by Microchip Technology for creating and optimizing embedded systems, particularly in automotive applications. It provides an extensive suite of tools that are essential for programming, debugging, and testing microcontrollers and digital signal controllers used in sophisticated systems like advanced safety brake systems for hill station vehicles.

#### **1. Overview and Features:**

- **Comprehensive Development Tools:** MPLAB X IDE offers a range of tools for coding, compiling, and debugging embedded applications. It supports various programming languages, including C and assembly, and is compatible with a wide range of Microchip microcontrollers and digital signal controllers.
- **Integrated Debugging:** The IDE includes powerful debugging features that allow developers to test and troubleshoot their code in real time. This includes features like breakpoints, watch variables, and step-by-step execution, which are crucial for ensuring that the firmware controlling MEMS sensors and braking systems operates correctly.
- **Graphical User Interface (GUI):** The intuitive GUI of MPLAB X IDE simplifies the development process by providing easy access to project management, code editing, and debugging tools. This user-friendly interface helps streamline development tasks and improve efficiency.

## **2. Application in Brake Systems:**

- **Firmware Development:** MPLAB X IDE is used to develop the firmware that interfaces with MEMS sensors and controls the braking system. The IDE supports writing, compiling, and optimizing the code that processes sensor data and manages braking actions in real-time.
- **Real-Time Testing:** With its integrated debugging tools, MPLAB X IDE enables developers to perform real-time testing of the braking system's firmware. This allows for the identification and correction of issues before deployment, ensuring that the brake system functions reliably under various driving conditions.

## **3. Benefits and Advantages:**

- **Efficient Development Process:** MPLAB X IDE streamlines the development process with its integrated tools and supportive features, reducing development time and effort. The environment's ability to manage complex projects and provide detailed debugging information enhances the development of robust and reliable braking systems.
- **Support for Advanced Features:** The IDE supports advanced development features such as code profiling and optimization, which are essential for maximizing the performance of embedded systems. This ensures that the braking system operates efficiently, with minimal latency in responding to sensor data.

## **4. Integration and Compatibility:**

- **Hardware Integration:** MPLAB X IDE is designed to work seamlessly with various Microchip development boards and hardware tools. This compatibility ensures that developers can test

their firmware directly on hardware prototypes, facilitating accurate validation of the braking system's performance.

- **Extensive Documentation and Support:** Microchip provides comprehensive documentation and support for MPLAB X IDE, including tutorials, reference manuals, and community forums. This support helps developers overcome challenges and leverage the full capabilities of the IDE.

## 5. Challenges and Considerations:

- **Learning Curve:** While MPLAB X IDE offers powerful features, there may be a learning curve for developers unfamiliar with the environment or Microchip's microcontroller architecture. Investing time in learning the IDE's capabilities is essential for maximizing its benefits.
- **Complexity Management:** Managing complex projects with numerous modules and components can be challenging. Effective project organization and version control practices are important for maintaining development efficiency and code quality.

In summary, MPLAB X IDE is a crucial tool for developing and optimizing the firmware of advanced safety brake systems for hill station vehicles. Its comprehensive development and debugging features enable the creation of high-performance embedded systems that enhance vehicle safety and control. By providing a robust environment for programming and testing, MPLAB X IDE supports the development of innovative braking solutions tailored to the demands of challenging terrains.

## 4. System Integration and Benefits

Integrating MEMS sensors with MPLAB X IDE in the design of an advanced safety brake system offers a sophisticated approach to



managing vehicle stability and safety, particularly in demanding environments like hill stations. This integration leverages the precision of MEMS sensors and the development capabilities of MPLAB X IDE to create a highly effective braking solution. Here's how this integration enhances the performance and reliability of the safety brake system:

### 1. **Continuous Monitoring and Adaptive Braking:**

- **Real-Time Data Collection:** MEMS sensors continuously gather data on various parameters such as acceleration, tilt, and lateral forces. This real-time data collection is crucial for understanding the vehicle's dynamic state and making immediate adjustments to braking forces as needed.
- **Adaptive Brake Response:** The data from MEMS sensors is used to adjust the braking force dynamically. For instance, if the sensors detect an increase in vehicle tilt or lateral forces due to a steep incline, the braking system can automatically apply additional force to counteract these conditions. This adaptive response helps maintain vehicle stability and prevent skidding, enhancing safety in challenging driving conditions.

### 2. **Enhanced Control and Stability:**

- **Improved Vehicle Control:** By integrating MEMS sensors, the braking system gains the ability to precisely control braking forces based on real-time data. This improved control helps manage the vehicle's behavior on steep gradients, sharp turns, and uneven terrain, reducing the risk of accidents caused by loss of traction or instability.
- **Traction Management:** MEMS sensors provide detailed information about the vehicle's interaction with the road surface. This data allows the braking system to adjust braking forces to

maintain optimal traction, ensuring that the vehicle remains stable and responsive even on slippery or uneven surfaces.

### 3. **Programming and Testing with MPLAB X IDE:**

- **Firmware Development:** MPLAB X IDE offers a comprehensive development environment for programming the microcontrollers that process sensor data and control the braking system. This environment supports various programming languages and provides tools for efficient coding and debugging, enabling the development of sophisticated algorithms that can handle complex braking scenarios.
- **System Optimization:** The IDE's debugging and testing tools allow engineers to fine-tune the braking system's firmware. Through iterative testing and optimization, developers can ensure that the system responds accurately to the specific demands of hill station driving. This includes adjusting algorithms to handle varying road conditions and vehicle dynamics effectively.
- **Real-Time Simulation:** MPLAB X IDE supports real-time simulation of the braking system, allowing engineers to test how the system behaves under different conditions. This capability is crucial for validating the system's performance and ensuring that it operates reliably in real-world scenarios.

### 4. **Benefits of Integration:**

- **Enhanced Safety:** The combined use of MEMS sensors and MPLAB X IDE ensures that the braking system can respond swiftly and accurately to changes in driving conditions, significantly enhancing vehicle safety. The system's ability to adapt to varying terrain and driving dynamics helps prevent accidents and improve overall driving confidence.

- **Increased Efficiency:** The integration streamlines the development process by providing a unified platform for sensor data processing and firmware development. This efficiency reduces development time and resources while improving the reliability and performance of the braking system.
- **Flexibility and Adaptability:** The modular design enabled by MEMS sensors and MPLAB X IDE allows for easy updates and modifications to the braking system. Engineers can quickly adapt the system to new requirements or incorporate additional features, ensuring that the braking system remains effective and up-to-date.

In summary, the integration of MEMS sensors with MPLAB X IDE offers significant benefits for the design and implementation of advanced safety brake systems. By leveraging real-time data and sophisticated development tools, this integration enhances vehicle stability, safety, and overall performance, particularly in challenging driving conditions such as hill stations.

## **5. Model and Working**

The Power Supply is given to the System through the step-down transformer that converts 230V AC supply to 12V AC supply, which is then sent to bridge rectifier that converts the 12V AC to a pulsating 12V DC supply. This 12V DC supply is then sent through a filter that converts pulsating DC to a pure DC supply and then using a voltage regulator the 12V DC supply is converted to 5V DC supply. This 5V DC supply is given to 40th pin of the Microcontroller that is Vee, 9th pin for the RESET button, LCD segment and driver IC (L293D). The port C of the microcontroller is connected to a pull up resistor and interfaced with LCD display. Port A is given to the MEMS sensor and port D is connected to the L293D driver IC. MEMS sensor is interfaced to micro controller using

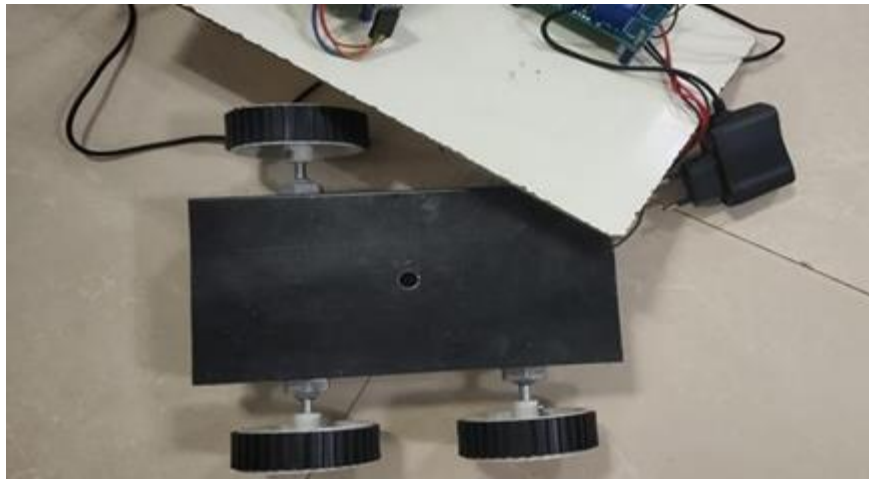
I2c protocol, microcontroller receives the data from the MEMS sensor and process it according to the data from the sensor appliances are operated.



**Fig 1. Model of Speed Control with Controller**

The output from the MEMS sensor is given to the Microcontroller which converts it into digital data. The output from the microcontroller is processed and shown in the LCD display and accordingly the motor is driven with the help of the driver IC. The driver IC is connected to the port D of the microcontroller and it controls the de motors. The direction of the motors and the speed control of the motors are controlled by the driver circuit.

The motors are connected to the wheels of the vehicle and as the speed changes the vehicles starts moving The MEMS sensor senses the acceleration of the vehicle and it is displayed in the LCD screen. As the vehicle moves the MEMS sensor displays the difference in the acceleration. As the vehicle climbs up the hill the speed of the motor speed changes as there is a change in the acceleration of the values in the X and Y plane. This speed is changed as it is already mentioned in the source code and accordingly the braking system is applied by decreasing the speed of the vehicle when the given acceleration values are reached.



**Fig 2. Model of Speed Control Vehicle**

A prototype of Safety Auto Brake System is designed. The prototype has been developed by the integrating features of all hardware components used. Presence of every component has been reasoned out and placed carefully thus contributing to the best working of the unit. In future, the Safety Auto Brake System can be used in many vehicles to avoid collisions and accidents. Regenerative braking can be used in the vehicles and energy is saved and is stored in the batteries that can be used for further purposes.

## **6. Conclusion**

The integration of MEMS sensors into safety auto brake systems represents a significant advancement in automotive technology. These sensors play a crucial role in enhancing vehicle safety by providing accurate and real-time data that is essential for effective braking, especially in challenging environments like hill stations. Their compact size, reliability, low power consumption, and cost-effectiveness make MEMS sensors highly suitable for a wide range of automotive applications, improving both performance and convenience.

As autonomous vehicle technology continues to evolve, the demand for MEMS sensors—particularly those related to optics and radio frequencies—is expected to grow. Companies that successfully address the technical challenges associated with these sensors will be at the forefront of this transformative era, driving innovations in vehicle safety and functionality.

In practical applications, such as the safety auto brake system, MEMS sensors are pivotal in preventing skidding during uphill travel. The system continuously monitors the vehicle's acceleration along the X and Y axes and transmits this data to the microcontroller. The microcontroller processes this information to adjust the speed of the braking motors, ensuring that the vehicle maintains stability as the road elevation changes. This automated response helps prevent accidents and enhances overall driving safety, underscoring the critical role of MEMS sensors in modern automotive systems.

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